Basic 2 Anisotropic Wet-etching of Silicon: Characterization and Modeling of Changeable Anisotropy

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Orientation Dependent Etching (Conventional Products)





Deep grooves on a (110) wafer

Diaphragm on a (100) wafer





Variation in etching profile on (100) silicon wafer







Variation in etching profile on (110) silicon wafer







Non-conventional 3-D microstructures using KOH anisotropic etching





Etching from both sides of a wafer

Two-step etching using two mask layers

K. Sato, et al, Proc. IFToMM Intl. Micromechanism Symp. (Tokyo, 1993.6) 155-160





Densely Arrayed Silicon Needles with a Pitch Distance of 200 microns Aiming at Transdermal Drug Delivery



M. Shikida et al.: Proc. MEMS-03 (Kyoto, 2003), 562

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New types of anisotropically etched 3-D structures: Curved, Sharp-cornered, 45-degree-angled V-grooves

Prem Pal: Jpn. J. Appl. Phys. 49 (2010)056702

Anisotropic chemical etching of Si from MEMS Point of View

- Etching Solutions KOH, "TMAH", "EDP", N₂H₄, NaOH, CsOH, etc.
- Chemical reaction
 - $Si + 2OH^{-} + 2H_{2}O$
 - \rightarrow Si(OH)₄ + H₂ \rightarrow SiO₂(OH)₂²⁻ + 2H₂
- What are known;
 Si (111) shows an extremely low etch rate.
 Etch-stop techniques: B-dope, Electro-chemical, etc.
- Applications Diaphragms, V-grooves, Cantilevers

---Limitations in fabricated shapes Many mysteries

 $Si + 2OH^- + 2H_2O \rightarrow SiO_2(OH)_2^{2-} + 2H_2$ This is the results of the following steps. (R. A. Wind, M.A. Hines, Surface Science 460 (2000) 21-38) = SiH₂ + OH⁻ + H₂O \rightarrow = SiHOH+ H₂ + OH⁻ $= SiHOH + OH^{-} + H_{2}O \rightarrow = Si(OH)_{2} + H_{2} + OH^{-}$ $(\equiv Si)_2 = Si(OH)_2 + 2H_2O \rightarrow 2(=Si-H) + Si(OH)_4$ $Si(OH)_4 + 2OH^- \rightarrow = SiO_2(OH)_2^2 + 2H_2O$

Characterization of Anisotropic Etching in macroscopic domains "Dangling-Bond Model" does not tell the truth, because no dynamics included. "Step Flow Model" explains anisotropy in the

vicinity of Si (111)

*Reversed anisotropy between KOH and TMAH *Etched shape clearly reflects atomic-step behavior in the vicinity of Si (111)

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Etching rate measurement

K. Sato et al.: Sensors and Actuators A-64 (1998) 87-93.

Hemispherical specimen

Before

After

• Maximum etching depth: 100 - 150 µm

Etching rate contour map for a KOH solution

Effects of a surfactant added to TMAH solution

K. Sato et al.: Sensors and Materials 13-5 (2001) 285-291.

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Poly-oxiethylene-alkyl-phenyl-ether

- Liquid easy to operate with little foaming
- Stable both in acid and alkaline solutions

Orientation-dependent effects of surfactant decreasing etch rates of silicon

K. Sato, et al., Sensors and Materials 13-5 (2001) 285-291.

Mask-corner undercut suppression

K. Sato, et al., Sensors and Materials 13-5 (2001) 285-291.

Orientations appearing on a vertex: (111) - (jj1) - (110)

Effects of the surfactant NCW

25 wt.% TMAH, 80 °C Etching depth: 50 μm

without NCW

with 2 wt.% NCW

Comparison of Structure Shape Etched from Same Mask Apertures

エッチングレートの表示例(ステレオ投影図)

Etching rate database

Anisotropic etching simulation system MICROCAD

現在、半導体プロセスをはじめとする多くの分野で CADシステムが重要な役割を果たしています。今 後、マイクロマシニングプロセスにおいてもCAD システムが重要な役割を果たすものと考えられま す。「MICROCAD」は、マイクロマシンCADシス テムの基礎となる単結晶シリコンの3次元エッチン グ形状シミュレータです。 ●単語シリコンを対象とした結晶質方性エッチングによる認気元形状シミュレーション ③専用データベースによりロエッチレートデータを管理 ③KOHのエッチレートデータを標準設定 ④マイクロマシニングブロとス度完全で計測したエッチレートデータの総み込み可能 ④GDS-IIフォーマットによるマスクデータの入出力 ④エッチレート、3次元形状のグラフィック出力 ④気い多いと増加度新ジール等との接触が可能 ④愛い鳥いと増作面置 ④UNIXフークステーション上で動作

Simulation results using MICROCAD

K. Sato, et al., Electronics and Communications in Japan, Part2, 83-4 (2000).

Simulation results using MICROCAD

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Simulation results using MICROCAD

Densely Arrayed Silicon Needles with a Pitch Distance of 200 microns for Transdermal Drug Delivery

M. Shikida et al. Sensors and Actuators A 116 (2004) 264–271

Arrayed Needle Fabrication Process: Combination of mechanical dicing and wet etching

M. Shikida et al. J. Micromech. Microeng. 14 (2004) 1462-1467

Etching time: (a) 0 min.

(b) 10 min.

(c) 20 min.

(d) 30 min.

(e) 40 min.

MICROCAD Simulation Results.

Etching time: (a) 0 min., (b) 5 min., (c) 10 min., (d) 15 min., (e) 20 min., (f) 25 min. Etching conditions: 34.0 wt.% KOH, 80°C

M. Shikida, et al, J. Micromech. Microeng. 14 (2004) 1462–1467

Etched deep grooves on (110) Si using a KOH water solution

Groove depth: 90 microns

KOH and TMAH show different types of anisotropy

K. Sato, et al.: Sensors and Actuators A-73 (1999) 131-137.

Relation between the etching rate distribution and etched profile

Characterization of Anisotropic Etching in macroscopic domains "Dangling-Bond Model" does not tell the truth, because no dynamics included. "Step Flow Model" explains anisotropy in the vicinity of Si (111)

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Conventional Explanation of Anisotropy in Etching

Hypothesis: Number of dangling bond appearing on the silicon surface determines the etching rate

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Step Flow Model for (111) Silicon

M. Elwenspoek, J. Electrochem. Soc. 140-7 (1993) 2075-80

Two types of stable steps on Si (111) surface (Mono-hydride and Di-hydride steps)

M.A. Gosalvez, et al. J. Micromech. Microeng. 17 (2007) S1-S26

Step movements determine profiles of pits and mesa on (111) silicon surface

<11 $\overline{2}$ >, <1 $\overline{2}$ 1>, < $\overline{2}$ 11>: _____ [11 $\overline{2}$] steps with 2 dangling bonds (2 backbonds)

Atomic level etching simulation in the vicinity of Si (111)

M.A. Gosalvez, et al. J. Micromech. Microeng. 17 (2007) S1-S26

- Is the atomic scale step flow model applicable to macroscopic etching? Etching solutions: KOH, TMAH Etching depth: tens of micrometers
- Does the number of dangling bonds determine the activeness of the surfaces or steps?

Characterization of Anisotropic Etching in macroscopic domains "Dangling-Bond Model" does not tell the truth, because no dynamics included. "Step Flow Model" explains anisotropy in the

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vicinity of Si (111)

Etch Pit Growth on (111) Silicon.

K. Sato, et al.: Sensors and Materials 15-2 (2003) 93-99.

Growth of individual pit traced during TMAH etching.

Optical microscope images with time increments

 Wafer preparation... Oxidization for 20 hours (3µm thick oxide) followed by oxide removal using HF.

etching condition...25%TMAH,
80° 30min

AFM image at the center of a pit etched with TMAH solution

Comparison in the shape of etch pits between KOH and TMAH

Step movements determine profiles of pits and mesa on (111) silicon surface

<112>, <121>, <211>: _____ [112] steps with 1 dangling bond (3 backbonds)

<11 $\overline{2}$ >, <1 $\overline{2}$ 1>, < $\overline{2}$ 11>: _____ [11 $\overline{2}$] steps with 2 dangling bonds (2 backbonds)

Differently oriented etch pit growth governed by the difference in activated step

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Difference in Etching Rate Contour Map between KOH and TMAH

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Step Flow Model for (111) Silicon

M. Elwenspoek, J. Electrochem. Soc. 140-7 (1993) 2075-80

Difference in surface structure depending on a direction of deviation from silicon (111)

- A i−hydride step

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Asymmetric increase in etching rate by angular deviation from (111) orientation

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Step movements determine profiles of pits and mesa on (111) silicon surface

<112>, <121>, <211>: _____ [112] steps with 1 dangling bond (3 backbonds)

<11 $\overline{2}$ >, <1 $\overline{2}$ 1>, < $\overline{2}$ 11>: _____ [11 $\overline{2}$] steps with 2 dangling bonds (2 backbonds)

- Is the atomic scale step flow model applicable to macroscopic etching?
 YES, in the vicinity of (111)
- Does the number of dangling bond determine the activeness of the surfaces or steps?
 NO
 (neither of the surface, nor of steps)

Characterization of Anisotropic Etching in macroscopic domains "Dangling-Bond Model" does not tell the truth, because no dynamics included. "Step Flow Model" explains anisotropy in the vicinity of Si (111)

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References

Etch mechanisms and characterization

R.A. Wind and M.A. Hines, Surface Science 460 (2000) 21-38.

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Effects of surfactant

K. Sato, et al., Sensors and Materials 13-5 (2001) 285-291.

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M.A. Gosalvez, et al., J. Micromech. and Microeng. 19-12 (2009) #125011.

Prem Pal, et al., Jpn. J. Appl. Phys. 49 (2010) 056702.

Needle Array

M. Shikida, et al., Proc. MEMS-03 (Kyoto, 2003), 562-565.

M. Shikida, et al., Sensors and Actuators A 116 (2004) 264–271.

M. Shikida, et al, J. Micromech. Microeng. 14 (2004) 1462–1467

Simulation system

K. Sato, et al, Proc. IFToMM Intl. Micromechanism Symp. (Tokyo, 1993.6) 155-160. K. Sato, et al., Electronics and Communications in Japan, Part2, 83-4 (2000). This publication was translated from Trans. of the Inst. of Electronics, Information and Communication Engineers C-II, J82-C-II, no. 3 (1999) 84-91.

